

GENSYS COMPACT PRIME IN REDUNDANCY APPLICATION APPLICATION NOTE

OPERATING SPECIFICATIONS

- The redundancy is a cold redundancy with an automatic switch Master to Slave and a manual switch Slave to Master:
 - The switch from failing controllers to Slave controllers is automatic without a manual intervention,
 - After a possible few seconds' power failure, the power plant will be automatically back to automatic power as it was before failure,
 - The switch from Slave controller (becoming Master) to the previously Master controller is done manually with an operator.
- The manual switch order from Slave controller (becoming Master) to the previously Master controller is done with a push button (mandatory push, no signal maintained) wiring in the input 6, terminal J1-15 from Slave controller.
- The Master controller cannot be the Slave and vice versa (watchdog signal is only sent from Master to Slave).
- The Slave controller is automatically forced in manual mode as long as it is the Slave. It cannot be changed to an auto mode or test mode.
- The **Slave** controller generates a lot of alarms/faults because it receives the same information as the one received from the **Master** controller (wired in parallel) but without control from the **Slave**. All alarms/faults on the **Slave** controller are usual and should not be taken into account. When the **Slave** controller takes the lead (loses watchdog), then its first action is to automatically reset all alarms/faults.



PROCEDURE TO RETURN ON THE MASTER AFTER FAULT

To switch the **Slave** controller (becoming **Master**) to the previous **Master** controller, please follow the procedure below:

- This operation is 100% manual,
- · Correct the fault which caused the loss of the Watchdog from the Master controller and therefore the switching to the Slave controller,
- Check the output of the Watchdog on the previous Master controller output N°3, terminal J1-6 is working. The signal is visible on the input N°5, terminal J1-14 of the Slave controller.
- · Reset manually all alarms/faults of the previous Master controller,
- Push the button return Slave -> Master.

For configuration files on «Master» and «Slave» products: please contact CRE TECHNOLOGY to receive it.





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WIRING SPECIFICATIONS

- All voltage measurements bus and genset are doubled.
- Necessity to use 2 transformer sets for current measurements (genset, mains, bus). One set for the Master controller and one set for the Slave controller.
- The digital outputs and analog outputs are switched between the **Master** controller and the **Slave** controller.





ASSIGNMENT OF I/O

GENSYS COMP	ACT PRIME Master & Slave	Terminals	GENSYS COMPACT PRIME Master	GENSYS COMPACT PRIME Slave
DIGITAL OUTPUTS	D0 1 -> Crank	J1-4	Х	Х
	D0 2 -> Fuel oil	J1-5	Х	Х
	DO 3 -> Watchdog OUT	J1-6	Х	Unused
	DO 4 -> Genset control by the Slave	J1-7	Unused	Х
RELAY OUTPUTS	R1 - > Genset breaker control (open)	J3-1	Х	Х
	R1 -> Common relay 1	J3-2	Х	Х
	R2 -> Genset breaker control (close)	J3-3	Х	Х
	R2 -> Common relay 2	J3-4	Х	Х
DIGITAL INPUTS	DI 1 -> Genset breaker feedback	J1-10	Х	Х
	DI 2 -> Remote start	J1-11	Х	Х
	DI 3 -> Emergency stop	J1-12	Х	Х
	DI 4 -> Unused	J1-13	Unused	Unused
	DI 5 -> Watchdog IN	J1-14	Unused	Х
	DI 6 -> Manual return from Slave to Master	J1-15	Unused	Х
	DI 7 -> Genset control by the Slave	J1-16	Х	Unused
CURRENT INPUTS	I1 -> Current input	J5-5	Х	Х
	I2 -> Current input	J5-4	Х	Х
	I3 -> Current input	J5-3	Х	Х
	Common -> Common current input	J5-6	Х	Х
VOLTAGE INPUTS	Bus N -> see attached single line diagram	J4-1	Х	Х
	Bus L1 -> see attached single line diagram	J4-4	Х	Х
	Bus L2 -> see attached single line diagram	J4-3	Х	Х
	Bus L3 -> see attached single line diagram	J4-2	Х	Х
	Gen N -> see attached single line diagram	J4-5	Х	Х
	Gen L1 -> see attached single line diagram	J4-8	Х	Х
	Gen L2 -> see attached single line diagram	J4-7	Х	Х
	Gen L3 -> see attached single line diagram	J4-6	Х	Х
CANBUS	CANL	J2-9	Х	Х
	CANH	J2-10	Х	Х

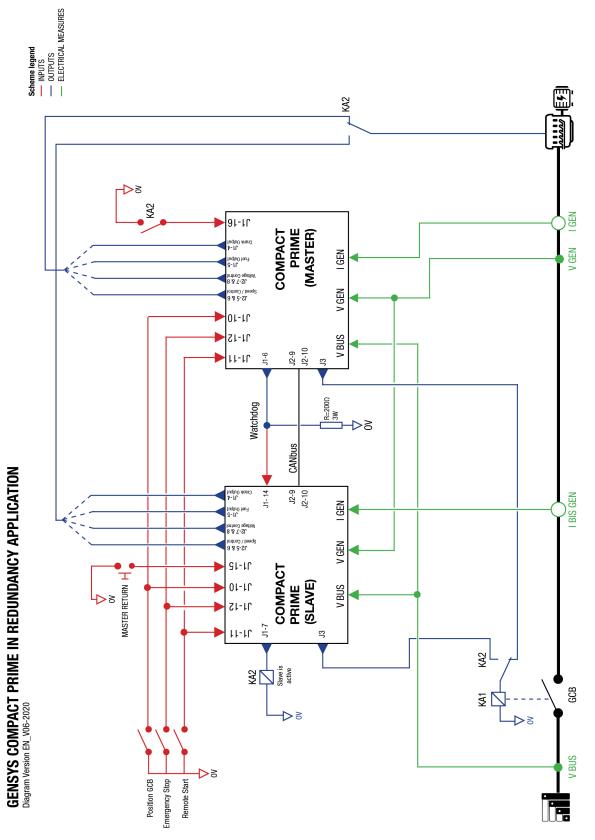


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